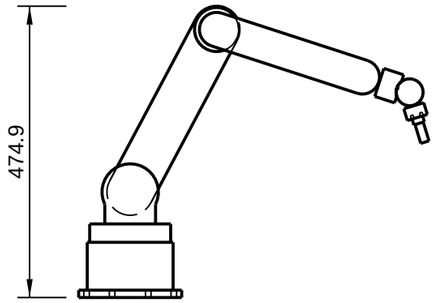
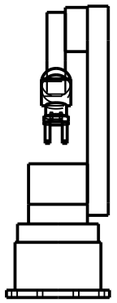






Item	Name / Part no.	Qty	Material*	Unit mass (g)	Remarks
1	Base	1		-	
2	J1 turret and J2 drive	1		-	
3	Upper arm	1		-	
4	J3 elbow drive	1		-	
5	Forearm	1		-	
6	J4 roll and J5 wrist	1		-	
7	J6 tool flange	1		-	
8	Parallel gripper	1		-	
*Material inferred from density.					

Part	Six-axis robot arm		
Scale (mm)	1:10 (mm)	Mass	-
Date	2026-10-24	Drawing	six-axis-arm
Projection	Third angle	Material	-